

a)

$$x(t) = 10 \sin 400t$$

$$c(t) = 30 \cos(300 \times 10^3 t)$$

$$Y(f) = X(f) \otimes C(f)$$

$$G_m(f) =$$

$$m(t) = 10 \sin 400t \times 30 \cos(300 \times 10^3 t)$$

$$= 300 \left(\frac{e^{-j400t} - e^{j400t}}{2j} \right) \times \cos(300 \times 10^3 t)$$

$$g(f) = \left(\frac{1}{2} X(f-f_c) + \frac{1}{2} X(f+f_c) \right) \times 300$$

$$= 150 \left(\frac{1}{2} \delta(f-20-1500) + \frac{1}{2} \delta(f+20-1500) + \frac{1}{2} \delta(f+20+1500) + \frac{1}{2} \delta(f-20+1500) \right)$$

~~1/2~~

91)

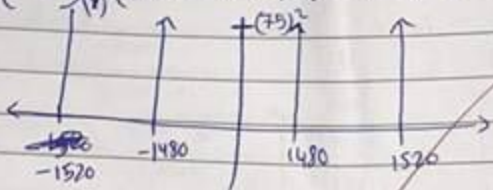
$$x(t) = 10 \sin 40\pi t \rightarrow \frac{5}{2j} \delta(f-20) + \frac{5}{2j} \delta(f+20)$$

$$c(t) = 30 \cos(3000\pi t)$$

$$M(f) = \frac{30}{2} X(f-f_c) + \frac{30}{2} X(f+f_c)$$

$$= 15 \left(\frac{10}{2j} \delta(f-20-1500) + \frac{10}{2j} \delta(f+20-1500) \right) + \frac{10}{2j} \left(5\delta(f+20+1500) + 5\delta(f+20+1500) \right)$$

$$M(f) = 75 \left(\delta(f-1520) + \delta(f-1480) + \delta(f+1480) + \delta(f+1520) \right)$$



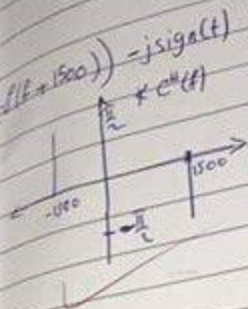
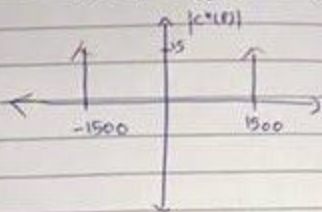
$$|M(f)|^2 = G_x(f) \otimes |C(f)|^2$$

$$25 * (15)^2 = 25 * 15 * 15$$

$$G_x(f) = |X(f)|^2 = \frac{25 * 25}{5^2} = 25$$

$$(b) c''(t) = c(t) \times \frac{1}{T} \theta$$

$$c''(f) = 30 \left(\frac{1}{2} f(f-1500) \right) + \frac{1}{2} f(f+1500) - j \text{sign}(f) \times c''(f)$$



$$(a) y'' + y' + 3y = 6x + 2x'$$

$$\textcircled{1} (j2\pi f)^2 + j2\pi f + 3) Y(f) = 6X(f) + j2\pi f X(f)$$

$Y(f)$

$$H(f) = \frac{Y(f)}{X(f)} = \frac{6 + j2\pi f}{(j2\pi f)^2 + j2\pi f + 3}$$

$$\textcircled{2} |H(f)| = \frac{\sqrt{36 + (2\pi f)^2}}{\sqrt{(3 - (2\pi f)^2)^2 + (2\pi f)^2}} \Rightarrow \text{not constant so it's with distortion (Amplitude)}$$

$$\angle H(f) = \tan^{-1} \left(\frac{2\pi f}{6} \right) - \tan^{-1} \left(\frac{2\pi f}{3 - (2\pi f)^2} \right) \Rightarrow \text{not linear so it's with phase distortion}$$

$$\textcircled{3} y(t) = |X(f)| |H(f)| e^{j(2\pi f t + \phi(f) + \theta(f))}$$

$$y(t) = 10 \times \frac{\sqrt{36 + (2\pi f)^2}}{\sqrt{(3 - (2\pi f)^2)^2 + (2\pi f)^2}} e^{j(2\pi f t + \frac{\pi}{3} + (\tan^{-1}(\frac{2\pi f}{6}) - \tan^{-1}(\frac{2\pi f}{3 - (2\pi f)^2}))}$$

$$f = \frac{200}{2\pi}$$

Amplitude
Phase

④)

$$① \quad r(t+3)(u(3-t)-u(t)) + -r(t)(u(t)-u(t-3))$$

$$x(t) = r(t+3)\Pi\left(\frac{t+1.5}{3}\right) - r(t)\Pi\left(\frac{t-1.5}{3}\right)$$

$$x(t) = \sum_{n=-\infty}^{\infty} r(t+3-nT_0)\Pi\left(\frac{t+1.5-nT_0}{3}\right) - r(t-nT_0)\Pi\left(\frac{t-1.5-nT_0}{3}\right)$$

$$\underline{\underline{T_0 = 6}}$$

② Half wave odd symmetry $\rightarrow X_n = 0$ for n : even.

$$V_n = \frac{1}{T} \int_P x(t) e^{-jn\omega t} dt$$

$$x(t) = r(t-6) \Pi\left(\frac{t-6}{2}\right) + r(t+8)$$

$$X(f) = F(r(t-6)) \otimes F\left(\Pi\left(\frac{t-6}{2}\right)\right) + 4 \operatorname{sinc}(4f) e^{j2\pi f 8}$$

$$F\left(\Pi\left(\frac{t-6}{2}\right)\right) = 2 \operatorname{sinc}(2f) e^{-j2\pi f 6}$$

$$F(r(t-6)) = \int_C e^{-j2\pi f t} dt$$

$$u=t \quad du = e^{-j2\pi f t}$$

$$du = dt \quad v = e^{-j2\pi f t}$$

$$\frac{dt}{2\pi f} e^{-j2\pi f t} \Big|_6^{\infty} = \frac{e^{-j2\pi f t}}{(j2\pi f)^2} \Big|_6^{\infty}$$

$$= 0 - \frac{j6}{2\pi f} e^{-j2\pi f 6} + \frac{e^{-j2\pi f 6}}{(j2\pi f)^2}$$

$$= \frac{3}{\pi f} e^{-j2\pi f 6} - \frac{e^{-j2\pi f 6}}{(2\pi f)^2}$$

Wrong

$$F(r(t-6) \Pi\left(\frac{t-6}{2}\right)) = \int_0^{\infty} 2 \operatorname{sinc}(2(\beta-k)) e^{-j2\pi f (\beta-k)} \left(\frac{3}{\pi k} e^{-j2\pi f k} e^{-j2\pi f k} \right) dk$$

$$X(f) = \int_{-\infty}^{\infty} 4 \operatorname{sinc}(4f) e^{j2\pi f 8}$$

2

$$a_n = \int_{-3}^0 (t+3) \cos n\omega t \, dt$$

$$u = t+3 \quad dv = \cos n\omega t$$

$$du = dt \quad v = \frac{\sin n\omega t}{n\omega}$$

$$\left. \frac{(t+3) \sin n\omega t}{n\omega} \right|_{-3}^0 - \left. \frac{\cos n\omega t}{(n\omega)^2} \right|_{-3}^0$$

$$\frac{3 \sin(3n\omega)}{n\omega} + 0 - \left(\frac{\cos(0) - \cos(-3n\omega)}{(n\omega)^2} \right)$$

$$a_n = \left(\frac{-1 + \cos(3n\omega)}{(n\omega)^2} \right) \frac{2}{10}$$

niodd

$$\omega_0 = \frac{2\pi}{6} = \frac{\pi}{3}$$

$$b_n = \frac{2}{10} \int_0^3 -t \sin n\omega t \, dt$$

$$u = -t \quad dv = \sin n\omega t$$

$$du = -dt \quad v = -\frac{\cos n\omega t}{n\omega}$$

$$\left. \frac{t \cos n\omega t}{n\omega} \right|_0^3 - \left. \frac{\sin n\omega t}{(n\omega)^2} \right|_0^3$$

$$\left(\frac{3 \cos 3n\omega}{n\omega} - \frac{\sin 3n\omega}{(n\omega)^2} \right) \frac{2}{10}$$

or Control
directly from the
 $a_n = 2 \operatorname{Re}(t_n)$
 $b_n = -2 \operatorname{Im}(t_n)$

$$x_n = \frac{a_n}{2} + \frac{b_n}{2j}$$

$$\left(\frac{\cos 3n\omega - 1}{(n\omega)^2} \right) \frac{1}{10} + \operatorname{Re} \left(\frac{3 \cos 3n\omega}{n\omega} - \frac{\sin 3n\omega}{(n\omega)^2} \right) \frac{1}{10}$$



$$\left. \begin{aligned}
 |x_n| \text{ for } n=1 \\
 |x_n| \text{ for } n=2 \Rightarrow 0
 \end{aligned} \right\} = \frac{1}{6^2} \left(\frac{\cos \pi - 1}{\left(\frac{\pi}{3}\right)^2} \right)^2 + \frac{1}{6^2} \left(\frac{9 \cos \pi}{\pi} \right)^2 - \sin \pi$$

$$|x_n|^2 \text{ for } n=3 = \frac{1}{6^2} \left(\frac{\cos 3\pi - 1}{\left(\frac{\pi}{3}\right)^2} \right)^2 + \frac{1}{6^2} \left(\frac{3 \cos 3\pi}{\pi} \right)^2 - \sin 3\pi$$

$$P_{av} = \sum |x_n|^2 = \frac{1}{6^2} \left(\left(\frac{-2}{\frac{\pi}{3}}\right)^2 + \frac{9^2}{\pi^2} + \left(\frac{-2}{\pi}\right)^2 + \left(\frac{-3}{\pi}\right)^2 \right)$$